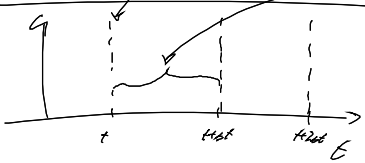


Wdh

feedback control

a.) instationäre Messung, stationäre Mess. Kontrolle



$$\epsilon t \rightarrow 0 \quad \dot{\tilde{q}} = Z_{FB} \tilde{q}$$

$$Z_{FB} = \sum_n M_n \sum_m Z_m M_n$$

hand. Kontrolle

$$\tilde{q} = \sum_n M_n q$$

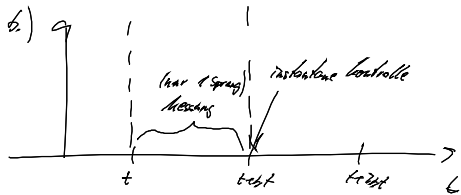
$$M_n M_n = \delta_{nn} M_n$$

(proj. Messung)

$$M_n q \hat{=} |k \times n| q |k \times n|$$

$$= M_n q M_n^\dagger$$

Beispiel: SET \rightarrow off. Regelgleichung \rightarrow Verdrängung des abt. GG



$$\epsilon t \rightarrow 0 \quad \dot{\tilde{q}} = Z_{FB} \tilde{q}$$

$$Z_{FB} = -i \tilde{H}_1 \rho$$

$$= \sum_{\nu \neq 0} \rho_{\nu} \left[\frac{1}{2} L_{\nu}^\dagger \rho + \frac{1}{2} \{L_{\nu}^\dagger L_{\nu} \rho\} \right]$$

$$H_{eff} = H - i \sum_{\nu} \rho_{\nu} L_{\nu}^\dagger L_{\nu}$$

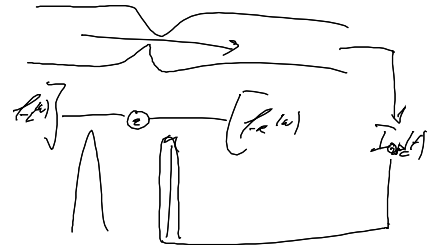
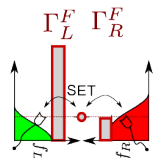
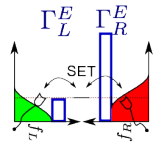
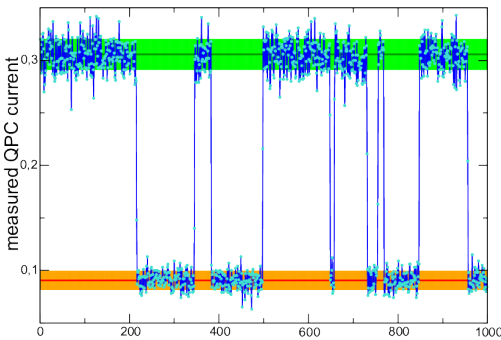
\rightarrow stabilisierter rezon. Zustand

$$Z_{FB} (1 \otimes \rho) = 0$$

= kein Delay zw. Messung & Kontrolle

7. Ausgewählte Anwendungen

7.1. Elektron. Masch. -Dämon



falls $\epsilon = const.$

\Rightarrow kein (bzgl. unmodifizierter) Energie transfer

Z_{FB}

$$\begin{pmatrix} -\Gamma_L^E f_L - \Gamma_R^E f_R \\ +\Gamma_L^E f_L e^{-i\omega t} + \Gamma_R^E f_R e^{-i\omega t} \end{pmatrix}$$

$$\begin{pmatrix} \Gamma_L^F (1-f_L) e^{i\omega t} + \Gamma_R^F (1-f_R) e^{i\omega t} \\ -\Gamma_L^F (1-f_L) - \Gamma_R^F (1-f_R) \end{pmatrix}$$

• Trajektorie a.) $P_{E|A} = 1 \quad P_{E|K} = 0$

$$\rightarrow P_{L, \text{mess}} \approx \Gamma_L^E \cdot f_L \cdot \delta t$$

$$P_{R, \text{mess}} \approx \Gamma_R^E \cdot f_R \cdot \delta t$$

$$P_{\text{wirts}} = 1 - P_{L, \text{mess}} - P_{R, \text{mess}}$$

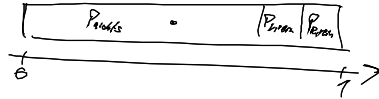
} 3 Möglichkeiten

b.) $P_{E|A} = 0 \quad P_{E|K} = 1$

$$P_{L, \text{mess}} \approx \Gamma_L^F (1-f_L) \cdot \delta t$$

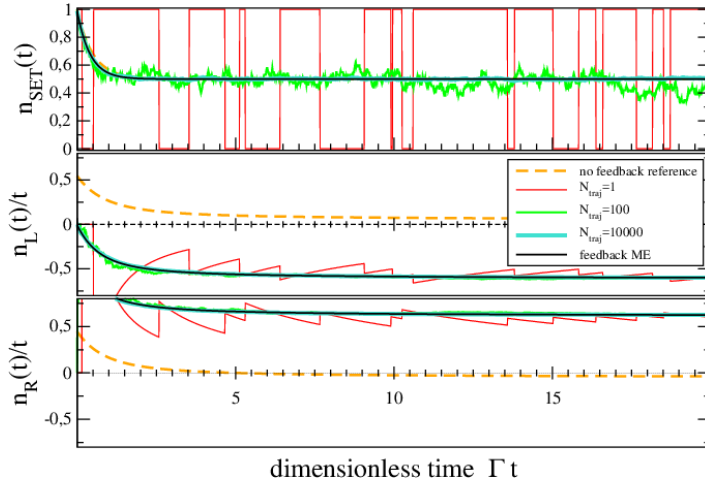
$$P_{R, \text{mess}} \approx \Gamma_R^F (1-f_R) \cdot \delta t$$

$$P_{\text{wirts}} = 1 - P_{L, \text{mess}} - P_{R, \text{mess}}$$



$$\bar{I}(k_u = k_e) \neq 0$$

$$P = -\bar{I}_A V = -\bar{I}_A / (\mu_u / k_e)$$



$$\Gamma_L^E = e^{+\delta \cdot \Gamma t} \quad \Gamma_R^E = e^{-\delta \cdot \Gamma t} \quad \Gamma_L^F = e^{-\delta \cdot \Gamma t} \quad \Gamma_R^F = e^{+\delta \cdot \Gamma t}$$

$\delta = 1$ feedback-Parameter

$$\hookrightarrow \delta \gg 1 \quad \bar{I}_A = e^{\delta \cdot \Gamma t} \frac{k_u(1-k_e)}{k_e(1-k_e)} \quad \frac{\beta_u \beta_e}{\mu_u / \mu_e} \quad \rho$$

falls $\beta_u = \beta_e = \beta$

$$\beta(\mu_u / \mu_e) = \ln \left[\frac{k_u(1-k_e)}{(1-k_e) \cdot k_e} \right] \quad k_u \in [0, 1]$$

$$\rho \approx \ln T \cdot \Gamma \cdot e^{\delta} \cdot 0.279 \quad \Gamma \cdot e^{\delta} \cdot \Delta t < 1$$

$$\text{Wann } \approx \ln T \cdot 0.279$$

$$Q_e \approx \ln T \cdot \ln 2 \approx \ln T \cdot 0.693$$

Landau-Prüfung

} keine Verdichtung des 2. HS

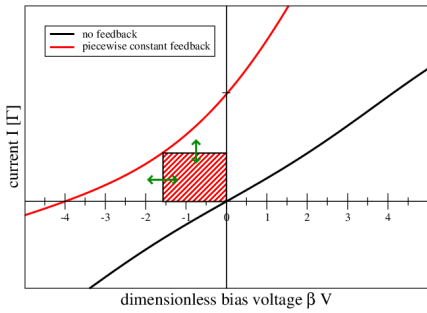
$$\text{CGF: } C(z, t) = \ln \langle e^{z \cdot X(t)} \rangle = \ln T \{ \rho(z, t) \} = \ln T \{ e^{Z(z) \cdot t} \rho_0 \}$$

$$\left(\lim_{t \rightarrow \infty} \right) \rightarrow \lambda_{\text{dom}}(z) \cdot t$$

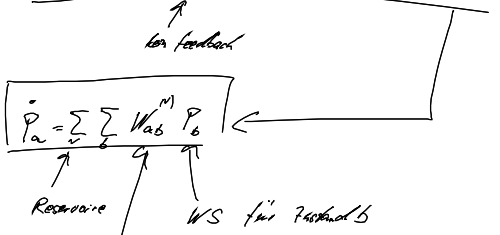
$$\text{falls } \lambda(-z) = \lambda(z + i\alpha) \rightarrow \frac{P_u}{P_n} = e^{z \cdot \tau}$$

$$\text{hier: } \ln \frac{P_n(t)}{P_n(0)} = e^{z(\beta \cdot \tau + \delta \tau)} = e^{z \cdot \beta \cdot (\tau - 2\tau)}$$

$$\tau = -\frac{\delta \tau}{\beta}$$



7.1.2 konventionelle Entropie bilanz in Postgl.



für $a \neq b$ Übergangsrate von $b \rightarrow a$ durch Res. \checkmark $W_{ab}^{(M)} \geq 0$

• $W_{aa}^{(M)} = - \sum_{b \neq a} W_{ba}^{(M)}$ WS-Erhaltung

• Reservoir in GG $\frac{W_{ji}^{(M)}}{W_{ij}^{(M)}} = e^{-\beta_V [E_j - E_i - \mu (N_j - N_i)]}$

→ Entropie $S(t) = - \sum_i P_i(t) \ln P_i(t)$

$\dot{S}(t) = - \sum_i \left[\dot{P}_i \ln P_i + P_i \dot{P}_i^{-1} \cdot \dot{P}_i \right] = - \sum_i \dot{P}_i \ln P_i$

$= - \sum_{ij} \sum_{\nu} W_{ij}^{(M)} P_j \ln \left(\frac{P_j}{P_i} \frac{W_{ij}^{(M)}}{W_{ji}^{(M)}} \right)$

$= + \sum_{ij} W_{ij}^{(M)} P_j \ln \left(\frac{W_{ij}^{(M)} P_j}{W_{ji}^{(M)} P_i} \right) + \sum_{ij} \sum_{\nu} W_{ij}^{(M)} P_j \left[\ln \left(\frac{W_{ij}^{(M)}}{W_{ji}^{(M)}} \right) - \ln P_j \right]$

Entropie Fluss

$\dot{S}_e^{(M)} = \sum_{ij} W_{ij}^{(M)} P_j \ln \frac{W_{ij}^{(M)}}{W_{ji}^{(M)}} = \beta_V [LE - \mu \dot{I}_a^{(M)}]$

log. Summen-ungl.: $\sum_{i=1}^n a_i \ln \left(\frac{a_i}{b_i} \right) \geq a \cdot \ln \frac{a}{b}$ $a_i, b_i \geq 0$

$a = \sum_i a_i$
 $b = \sum_i b_i$

$\dot{S}_i = \sum_{ij} \sum_{\nu} W_{ij}^{(M)} P_j \ln \left[\frac{W_{ij}^{(M)} P_j}{W_{ji}^{(M)} P_i} \right]$
"impossible" Entropie-Prod.-rate

$$\dot{S} - \sum_{\nu} \beta_{\nu} [\dot{I}_{E}^{(\nu)} - \mu_{\nu} \dot{I}_{A}^{(\nu)}] = \dot{S}_i \geq 0$$

System-Entropie Änderung der Entropie in den Bädern

$$dH = TdS - pdV + \mu dN \quad \text{in GG}$$

$$dS_{res} = \frac{1}{T} dH_{res} - \frac{1}{\mu} \mu dN_{res}$$

$$\frac{dH_{res}}{dt} = -\dot{I}_E$$

$$\frac{dN_{res}}{dt} = -\dot{I}_A$$

für BHS-Nachgelösung:

$$H_S |i\rangle = E_i |i\rangle \quad [H_S H_S] = 0$$

$$H_S |j\rangle = N_j |j\rangle$$

$$\langle i | \rho^{(M)} | i \rangle = \sum_j W_{ij} \langle j | \rho | j \rangle$$

$$\dot{S}_i = - \sum_{\nu} T_{\nu} \left\{ \sum_j W_{ij} \left[\ln \rho_{ij} - \ln \rho_{jj} \right] \right\}$$

$$= \sum_{\nu} \left[\dot{S}_{i, \nu}^{(M)} + \dot{S}_{i, \nu}^{(L)} \right]$$

entspricht der Rategleichung

7.1.3. Entropiebilanz mit feedback

$$\dot{P}_i = \sum_j \sum_{\nu} W_{ij}^{(\nu)} P_j$$

← feedback

Energie-Übertrag bei $j \rightarrow i$:

$$\Delta E_{ij} = \underbrace{(E_i^{(i)} - E_i^{(j)})}_{\text{Wärme}} + \underbrace{(E_i^{(i)} - E_i^{(j)})}_{\text{Kontroll-Arbeit}}$$

$$\dot{I}_E^{(M)} = \sum_{ij} [E_i^{(i)} - E_i^{(j)}] W_{ij}^{(M)} P_j$$

$$\dot{I}_A^{(M)} = \sum_{ij} (N_i - N_j) W_{ij}^{(M)} P_j$$

$$\dot{I}_E^{(L)} = \sum_{ij} [E_i^{(i)} - E_i^{(j)}] W_{ij}^{(L)} P_j$$

$$\dot{E} = \underbrace{\sum_{\nu} \mu_{\nu} \dot{I}_{A}^{(\nu)}}_{\text{chem. Arbeit}} + \underbrace{\dot{I}_E^{(L)}}_{\text{Kontrollarbeit}} + \underbrace{\sum_{\nu} [\dot{I}_E^{(M)} - \mu_{\nu} \dot{I}_{A}^{(\nu)}]}_{\text{Wärme}}$$

$$\dot{S} = \dot{S}_i + \dot{S}_e$$

$$\sum_{ij} \sum_{\nu} W_{ij}^{(\nu)} P_j \cdot \ln \left[\frac{W_{ij}^{(\nu)} P_j}{W_{ji}^{(\nu)} P_i} \right] \geq 0$$

$$\frac{W_{ij}^{(M)}}{W_{ji}^{(M)}} = e^{\beta [E_i^{(i)} - E_i^{(j)}] - \mu (N_i - N_j)} e^{-\beta E_i^{(i)}} e^{-\beta E_j^{(j)}}$$

in Endeffekt:

$$\dot{S}_i = \dot{S} - \sum_{\nu} \beta_{\nu} \dot{Q}^{(\nu)} + \dot{I}_1 + \dot{I}_2 \stackrel{!}{\geq} 0$$

$$= \sum_{ij} \sum_{\nu} W_{ij}^{(\nu)} P_j \cdot \Delta E_{ij}^{(\nu)}$$

→ Entropie (bzw. Informationsströme) durch die Kontrollschleife nicht berücksichtigt werden.

