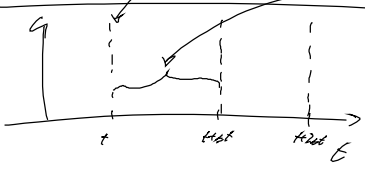


Wdh

feedback control

a) instabile Messung, stabilisierte Messung Kontrolle



$$\dot{x} \rightarrow 0 \quad \dot{y} = Z_{FB} \dot{y}$$

$$Z_{FB} = \sum_n M_n \sum_m Z_m M_n$$

hand. Kontrolle

$$\dot{y} = \sum_n M_n \dot{y}$$

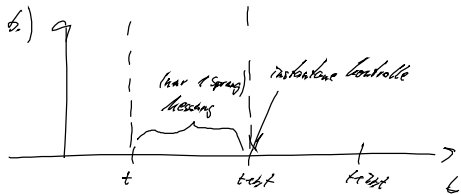
$$M_n M_n = \delta_{nn} \cdot M_n$$

(proj. Messung)

$$M_n \dot{y} \hat{=} |k \times n| \dot{y} |k \times n|$$

$$= M_n \dot{y} M_n^+$$

Beispiel: SET \rightarrow off. Regelgleichung \rightarrow Verdichtung des det. GG



$$\dot{x} \rightarrow 0 \quad \dot{y} = Z_{FB} \dot{y}$$

$$Z_{FB} = -i \sum_n \dot{y}$$

$$= \sum_n \sum_m \dot{y} \left[\frac{1}{2} (L_m^+ L_n + L_n^+ L_m) \dot{y} \right]$$

$n, m \geq 0$

$$V_{eff} = H - i \sum_n \dot{y} L_n^+ L_n$$

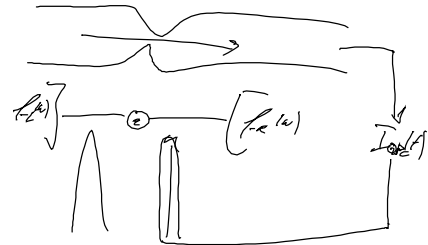
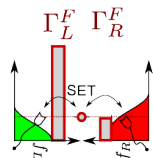
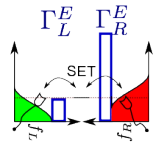
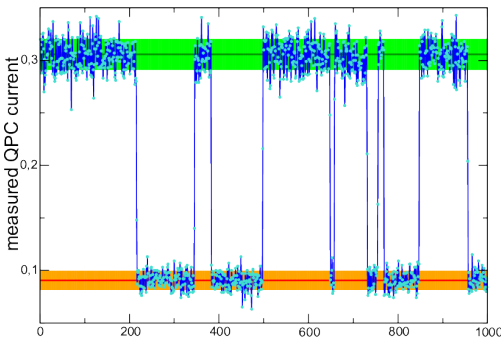
\rightarrow stabilisierte rezon. Zustand

$$Z_{FB} (1 \times 1) = 0$$

• kein Delay zw. Messung & Kontrolle

7. Ausgewählte Anwendungen

7.1. Elektron. Maxwell-Dämon



falls $\epsilon = const.$

\Rightarrow kein (bz. unumkehrbarer) Energie transfer

Z_{FB}

$$\begin{pmatrix} -\Gamma_L^E \cdot \Gamma_L^E - \Gamma_R^E \cdot \Gamma_R^E \\ + \Gamma_L^E \cdot \Gamma_R^E e^{-i\epsilon t} + \Gamma_R^E \cdot \Gamma_L^E e^{-i\epsilon t} \end{pmatrix}$$

$$\frac{\Gamma_L^F (1 - \Gamma_L^F) e^{i\epsilon t} + \Gamma_R^F (1 - \Gamma_R^F) e^{i\epsilon t}}{-\Gamma_L^F (1 - \Gamma_L^F) - \Gamma_R^F (1 - \Gamma_R^F)}$$

• Trajektorie a.) $P_{E(t)} = 1 \quad P_F(t) = 0$

$$\rightarrow P_{L, rez} \approx \Gamma_L^E \cdot \Gamma_L^E \cdot \epsilon t$$

$$P_{R, rez} \approx \Gamma_R^E \cdot \Gamma_R^E \cdot \epsilon t$$

$$P_{wirts} = 1 - P_{L, rez} - P_{R, rez}$$

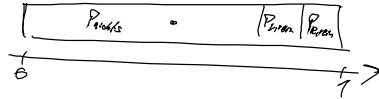
} 3 Möglichkeiten

b.) $P_E(t) = 0 \quad P_F(t) = 1$

$$P_{L, rez} \approx \Gamma_L^F (1 - \Gamma_L^F) \cdot \epsilon t$$

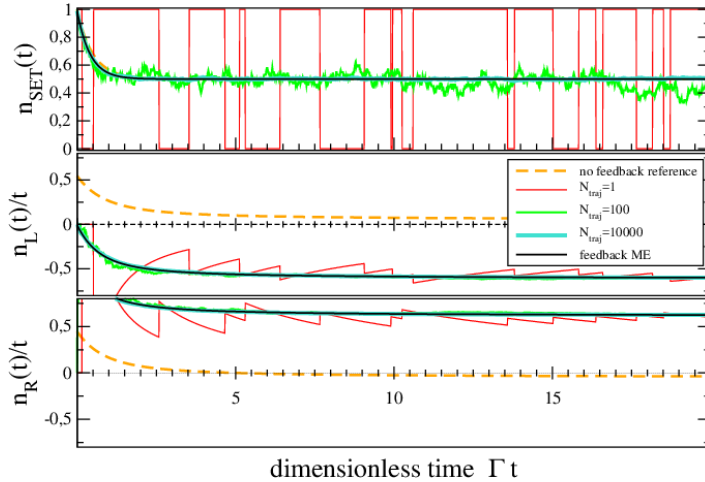
$$P_{R, rez} \approx \Gamma_R^F (1 - \Gamma_R^F) \cdot \epsilon t$$

$$P_{wirts} = 1 - P_{L, rez} - P_{R, rez}$$



$$\bar{I}(f_u = f_e) \neq 0$$

$$P = -\bar{I}_A V = -\bar{I}_A (f_u - f_e)$$



$$\Gamma_L^E = e^{+\delta \cdot \Gamma} \quad \Gamma_R^E = e^{-\delta \cdot \Gamma} \quad \Gamma_L^F = e^{-\delta \cdot \Gamma} \quad \Gamma_R^F = e^{+\delta \cdot \Gamma}$$

$\delta = 1$ feedback-Parameter

$$\hookrightarrow \delta \gg 1 \quad \bar{I}_A = e^{\delta \cdot \Gamma} \frac{f_u(1-f_e)}{f_u(1-f_e)} \quad \frac{\beta_u \beta_e}{\mu_u \mu_e} \quad \rho$$

falls $\beta_u = \beta_e = \beta$

$$\beta(f_u - f_e) = \ln \left[\frac{f_u(1-f_e)}{(1-f_u) \cdot f_e} \right] \quad f_u \in [0, 1]$$

$$P \approx \ln T \cdot \Gamma \cdot e^{\delta} \cdot 0.279 \quad \Gamma \cdot e^{\delta} \cdot t < 1$$

$$W_{\text{max}} \approx \ln T \cdot 0.279$$

$$Q \approx \ln T \cdot \ln 2 \approx \ln T \cdot 0.693$$

Landauer-Prinzip

} keine Verletzung des 2. HS

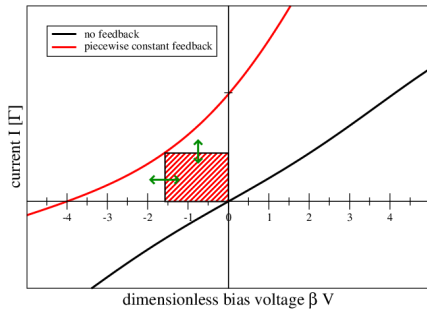
$$\text{CGF: } C(z, t) = \ln \langle e^{z \cdot X(t)} \rangle = \ln T_r \{ \rho(z, t) \} = \ln T_r \{ e^{z(x) \cdot t} \rho_0 \}$$

$$\left(\lim_{t \rightarrow \infty} \right) \rightarrow \lambda_{\text{dom}}(z) \cdot t$$

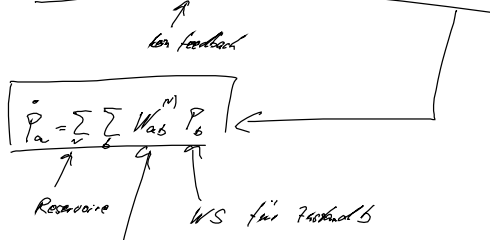
$$\text{falls } \lambda(-x) = \lambda(x + i\alpha) \rightarrow \frac{P_x}{P_{-x}} = e^{x \cdot \alpha}$$

$$\text{hier: } \lim_{t \rightarrow \infty} \frac{P_{n(t)}}{P_{-n(t)}} = e^{x(\beta \cdot n + \delta)} = e^{x \cdot \beta \cdot (n - 2^k)}$$

$$\alpha = -\frac{\delta \beta}{\beta}$$



7.1.2 konventionelle Entropie bilanz in Postgl.



für $a \neq b$ Übergangsrate von $b \rightarrow a$ durch Res. \checkmark $W_{ab}^{(M)} \geq 0$

• $W_{aa}^{(M)} = - \sum_{b \neq a} W_{ba}^{(M)}$ WS-Erhaltung

• Reservoir in GG $\frac{W_{ij}^{(M)}}{W_{ji}^{(M)}} = e^{-\beta_V [E_j - E_i - \mu (N_j - N_i)]}$

→ Entropie $S(t) = - \sum_i P_i(t) \ln P_i(t)$

$\dot{S}(t) = - \sum_i \left[\dot{P}_i \ln P_i + P_i \dot{P}_i^{-1} \cdot \dot{P}_i \right] = - \sum_i \dot{P}_i \ln P_i$

$= - \sum_{ij} W_{ij}^{(M)} P_j \ln \left(\frac{P_j}{P_i} \frac{W_{ij}^{(M)}}{W_{ji}^{(M)}} \right)$

$= + \sum_{ij} W_{ij}^{(M)} P_j \ln \left(\frac{W_{ij}^{(M)} P_j}{W_{ji}^{(M)} P_i} \right) + \sum_{ij} \sum_c W_{ij}^{(M)} P_j \left[\ln \left(\frac{W_{ij}^{(M)}}{W_{ji}^{(M)}} \right) - \ln P_j \right]$

Entropie Fluss

$\dot{S}_{e}^{(M)} = \sum_{ij} W_{ij}^{(M)} P_j \ln \frac{W_{ij}^{(M)}}{W_{ji}^{(M)}} = \beta_V [LE - \mu \dot{I}_a^{(M)}]$

log. Summen-ungl.: $\sum_{i=1}^n a_i \ln \left(\frac{a_i}{b_i} \right) \geq a \ln \frac{a}{b}$ $a_i, b_i \geq 0$

$a = \sum_i a_i$
 $b = \sum_i b_i$

$\dot{S}_i = \sum_{ij} \sum_c W_{ij}^{(M)} P_j \ln \left[\frac{W_{ij}^{(M)} P_j}{W_{ji}^{(M)} P_i} \right]$
"impossible" Entropie-Prod.-rate

$$\dot{S} - \sum \beta_r [\overline{I_E^{(r)}} - \mu_r \overline{I_A^{(r)}}] = \dot{S}_i \geq 0$$

System-Entropie Änderung der Entropie in den Bädern

$$dU = TdS - pdV + \mu dN \quad \text{in GG}$$

$$dS_{res} = \frac{1}{T} dU_{res} - \frac{1}{\mu} \mu dN_{res}$$

$$\frac{dU_{res}}{dt} = -\overline{I_E}$$

$$\frac{dN_{res}}{dt} = -\overline{I_A}$$

für BHS-Nachgelösung:

$$H_S |i\rangle = E_i |i\rangle \quad [H_S H_S] = 0$$

$$H_S |j\rangle = N_j |j\rangle$$

$$\langle i | \rho^{(M)} | i \rangle = \sum_j W_{ij} \langle j | \rho | j \rangle$$

$$\dot{S}_i = - \sum_r \{ \lambda^{(r)} \rho [\ln \rho - \ln \rho^{(r)}] \}$$

$$= \sum_r \left[\dot{S}_{i,r} + \dot{S}_{i,z} \right]$$

entspricht der Rategleichung

7.1.3. Entropiebilanz mit feedback

$$\dot{P}_i = \sum_j \sum_k W_{ij}^{(k)} P_j$$

← feedback

Energie-Übertrag bei $j \rightarrow i$:

$$\Delta E_{ij} = \underbrace{(E_i^{(i)} - E_j^{(i)})}_{\text{Wärme}} + \underbrace{(E_i^{(i)} - E_j^{(j)})}_{\text{Kontroll-Arbeit}}$$

$$\overline{I_E^{(i)}} = \sum_j [E_i^{(i)} - E_j^{(i)}] W_{ij}^{(i)} P_j$$

$$\overline{I_A^{(i)}} = \sum_j (N_i - N_j) W_{ij}^{(i)} P_j$$

$$\overline{I_E^{(j)}} = \sum_i [E_i^{(j)} - E_i^{(i)}] W_{ij}^{(j)} P_i$$

$$\dot{E} = \underbrace{\sum \mu_r \overline{I_A^{(r)}}}_{\text{chem. Arbeit}} + \underbrace{\overline{I_E^{(fb)}}}_{\text{Kontrollarbeit}} + \underbrace{\sum [\overline{I_E^{(i)}} - \mu_r \overline{I_A^{(r)}}]}_{\text{Wärme}}$$

$$\dot{S} = \dot{S}_i + \dot{S}_e$$

$$\sum_i \sum_j W_{ij}^{(i)} P_j \cdot \ln \left[\frac{W_{ij}^{(i)} P_j}{W_{ji}^{(i)} P_i} \right] \geq 0$$

$$\frac{W_{ij}^{(i)}}{W_{ji}^{(i)}} = e^{\beta [E_i^{(i)} - E_j^{(i)}] - \mu_r (N_i - N_j)} e^{-\beta E_i^{(i)}} e^{-\beta E_j^{(i)}}$$

in Endeffekt:

$$\dot{S}_i = \dot{S} - \sum_r \beta_r \dot{Q}^{(r)} + \overline{I_A^{(1)}} + \overline{I_A^{(2)}} \stackrel{!}{=} 0$$

$$= \sum_i \sum_j W_{ij}^{(i)} P_j \cdot \Delta S_{ij}^{(i)}$$

→ Entropie (bzw. Informationsströme) durch die Kontrollschleife nicht berücksichtigt werden.

